C.U.SHAH UNIVERSITY Summer Examination-2018

Subject Name : Advanced Process Control Subject Code : 4TE07APC1 **Branch : B.Tech (IC)** Semester : 7 Date : 26/03/2018 Time : 10:30 To 01:30 Marks: 70 Instructions: (1) Use of Programmable calculator & any other electronic instrument is prohibited. (2) Instructions written on main answer book are strictly to be obeyed. (3) Draw neat diagrams and figures (if necessary) at right places. (4) Assume suitable data if needed. Q-1 Attempt the following questions: (14)Control systems based on these linear methods are generally successful in the process 01 a) industries because (a) The control system maintains the process in a small range of operating variables (b) Many processes are not highly nonlinear (c) Most control algorithms and designs are not sensitive to reasonable $(\pm 20\%)$ model errors due to nonlinearities (d) All the above **b**) Adjusting of controller gain to achieve the desired control performance is known as 01 (a) Feedforward (b) Gain scheduling (c) Ratio (d) None of them c) Simple integrating system has _____ order and _____ type. 01 (a) 2 & 0 (b) 1 & 0 (d) 1 & 1 (c) 0 &1 Implementation issue of a cascade control is/are____ **d**) 01 (b) Bumpless transfer (a) Windup in loop (c) Cost is more (d) All of the above Inner loop of cascade control is also known as _____ 01 e) (a) Master (b) Slave (c) Primary (d) Controller The type 0 system has _____ at the origin. **f**) 01 (b) One pole (a) No pole (c) Simple pole (d)None of the above Feed forward controller play's an important role in stability of system 01 **g**) (a) True (b) false Feed forward controller is a 01 h) (a) Lead lag compensator (b) An integrator (c) An differentiator (d) None of the above In ratio control the stem whose flow is not control is called as 01 **i**) (a) Wild (b) Manipulated (c) Controlled (d) None of these Cascade control in loop is implemented because 01 **j**)

(a) Single-loop control does not provide satisfactory control performance.

(b) A measured secondary variable is available.



	(c) Both a and b					
	(d) None of above					
	Characteristic such that a given percentage change in stem position produces an					
k)	equivalent change in flow at constant pressure drop is known as					
	(a) Linear	(b) Quick opening	(c) Equal percent	ntage (d) None of them		
I)	Feed forward control cannot eliminate			01		
1)	(a) Disturbance	(b) Noise	(c) Offset	(d) None of them		
m)	In non-linear system transfer function		with input and time		01	
	(a) Constant	(b) Vary	(c) Can't say	(d) None of the above		
	Impulse response of system is called as _			of a system.	01	
n)	(a) Transfer function		(b) Frequency response			
	(c) Delay		(d) None of the	ese		

Attempt any four questions from Q-2 to Q-8

Q-2	a)	Attempt all questions Explain step analysis method for finding three parameter model (gain, time constant and dead time) with suitable diagram.	(14) 10
	b)	Give the difference between feedback and feed forward control system.	04
Q-3	,	Attempt all questions	(14)
	a)	Explain PID controller and explain the procedure of its tuning	07
	b)	With the help of diagram explain ratio control and its configuration.	07
Q-4		Attempt all questions	(14)
	a)	Derive mathematical model of first order of system and plot the graph for the same.	07
	b)	Explain MPC with the help of diagram.	07
Q-5		Attempt all questions	(14)
	a)	With the help of diagram explain split range control	07
	b)	Explain in detail the implementation issue, advantages & disadvantages of cascade controller	07
Q-6		Attempt all questions	(14)
	a)	Explain deterministic loop calculation for improving the performance of non linear	07
	b)	Write a short note on Feedforward control.	07
0-7		Attempt all questions	(14)
Q-7	a)	Give control analysis of a non-linear process with linear feedback control	(14)
	a) h)	Explain the control objective for controlling a system	07
	N)		07
Q-8		Attempt all questions	(14)
-	a)	Write a short note on cascade control	07

